## **Subject Description Form**

Subject Code	EE3002 / EE3002A / EE3002B				
Subject Title	Electromechanical Energy Conversion				
Credit Value	3				
Level	3				
Pre-requisite/ Co-requisite/ Exclusion	Pre-requisite for EE3002: EE2002 Pre-requisite for EE3002A: EE2002A Pre-requisite for EE3002B: EE2002B				
Objectives	<ol> <li>To provide students a general knowledge on common types of electric machines.</li> <li>To provide students the basic techniques of steady-state electric machine analysis.</li> </ol>				
Intended Learning Outcomes	<ul> <li>Upon completion of the subject, students will be able to:</li> <li>a. Explain the construction, operating principles, performance characteristics, control and applications of major types of rotating electric machines.</li> <li>b. Analyse the steady-state performance of electric machines using appropriate equivalent circuit models.</li> <li>c. Operate practical electric machines and to conduct relevant tests and experiments.</li> <li>d. Present results of electric machine studies in the form of tables, graphs, and written reports.</li> </ul>				
Subject Synopsis/ Indicative Syllabus	<ol> <li>Introduction: Principles of motors and generators. Materials for electric machines. Types of electric machines and applications. Losses and efficiency.</li> <li>Machine rating: Temperature rise and cooling methods. Heating and cooling curves. Thermal ratings. Machine nameplate.</li> <li>Windings: Phase and commutator windings. Winding factors. E.M.F. equation. Harmonics. Production of rotating magnetic field.</li> <li>D.C. machines: Construction. E.M.F equation. Armature reaction and commutation. Characteristics of shunt, series and compound machines. Testing. Speed control. Universal motor. Brushless d.c. motor.</li> <li>Synchronous machines: Construction. Synchronous impedance. Voltage regulation. Synchronising. Performance on infinite busbars. Power/load angle relationship. Stability. Synchronous motor.</li> <li>Induction machines: Squirrel cage and wound-rotor types. Equivalent circuit. Torque-slip relationship. Starting, braking and generating. Testing. Speed control. Single-phase induction motors.</li> </ol>				
	Performance evaluation of a three-phase cage induction motor. Synchronous generator synchronization.				

Teaching/Learning Methodology	Delivery of the subject is mainly throu Excel programmes are used to clar conducting 'what-if' analysis. Laborat operation and control of practical m practise written and graphic presentation Teaching/Learning Methodology	ify concepts tory work prov nachines, whil	of electric vides stude	machine nts hands	s learnt -on expe ables stu	and for prience in	
	Lectures Tutorials Laboratory work			 ✓	 ✓	u	
				· ✓			
				· •	✓	$\checkmark$	
					•	•	
Assessment Methods in	Specific assessment methods/tasks	becific assessment methods/tasks % weighting		Intended subject learning outcomes to be assessed			
Alignment with Intended Learning Outcomes			a	b	c	d	
	1. Examination	60%	✓	$\checkmark$	✓	$\checkmark$	
	2. Mid-term Test	20%	✓	$\checkmark$	✓		
	3. Laboratory work and reports	15%		$\checkmark$	$\checkmark$	✓	
	4. Assignment	5%	✓	$\checkmark$			
	Total	100%					
	It is a fundamental subject on electric machines and transformers. The outcomes on concepts, operating principles and applications are assessed by the usual means of assignment, tests, and examination. The outcomes on practical operation of electric machines and technical communication are evaluated by laboratory work and reports.						
Student Study	Class contact:						
Effort Expected	Lecture/Tutorial				33 Hrs.		
	<ul> <li>Laboratory</li> </ul>				6 Hrs.		
	Other student study effort:						
	<ul> <li>Revision, self-study, and assignment</li> </ul>				48 Hrs.		
	<ul> <li>Write-up of laboratory reports</li> </ul>			18 Hrs.			
	Total student study effort				105 Hrs.		
Reading List and References	<ul> <li>Reference books:</li> <li>1. M.S. Sarma And M.K.Pathak, "Electric Machines", Cengage Learning, 2012.</li> <li>2. S.A. Nasar, Schaum's Outline of Theory and Problems of Electric Machines and Electromechanics, 2<sup>nd</sup> Edition, McGraw-Hill, 1998</li> </ul>						

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